



GOES-R Algorithm Working Group (AWG)

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Wayne MacKenzie, AWG Support

AWG Application Team Leads and Members

NOAA/NESDIS Center for Satellite Applications and Research



OUTLINE



- The Algorithm Working Group (AWG): An Introduction
- AWG Current Efforts in GOES-R Level-2 Product Development and Validation
- Level-2 Product Calibration/Validation Planning
- Summary



The GOES-R AWG: An Introduction

- *Mission*
- *Relationship and synergies with other GOES-R Programs*
- *Makeup*
- *Roles and responsibilities*



Algorithm Working Group

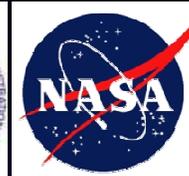


PURPOSE: To select, develop, test, validate, and demonstrate Level-2+ product algorithms that will meet GOES-R requirements and provide them to the GOES-R Ground Segment. Provide sustained life cycle validation and Level-2 product enhancements.

- Leverages nearly 100 scientists from NOAA, NASA, NOAA's Cooperative Institutes (CIMSS, CIRA, CICS), and Universities
- Applies first-hand knowledge of algorithms developed for POES, GOES, DMSP, AIRS, MODIS, and MetOP.
- Leverages other programs & experiences (GOES, POES, MODIS, AIRS, IASI, NPOESS and other prototype instruments and international systems)
- Seeks to facilitate algorithm consistency across satellite platforms -- prerequisite for Global Earth Observation System of Systems (GEOSS)



AWG Capabilities and Experience

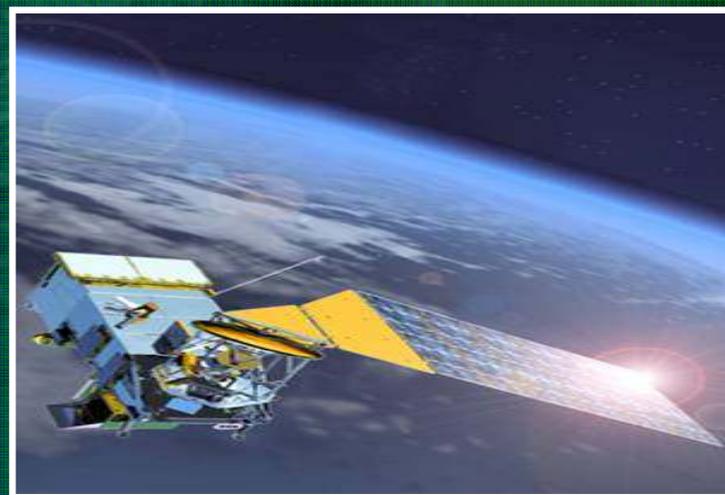


End-to-End Capabilities

- Instrument Trade Studies
- Proxy Dataset Development
- Algorithm Development
- Product Demonstration Systems
- Development of Cal/Val Tools
- Integrated Cal/Val Enterprise System
- Application Development
- User Readiness
- Sustained Product Validation
- Algorithm and application improvements

Experience in Algorithm Delivery and Implementation

- Developed, tested, delivered, and implemented operational product generation systems
 - POES
 - GOES
 - DMSP (NOAA applications)
 - AIRS, MODIS
 - METOP (IASI, GOME, ASCAT)
 - NPOESS (NDE Project)



AWG brings capabilities that are applicable through the lifetime of the GOES-R Program



GOES-R Algorithm/Product Readiness



<p>Underpinning Research & Development (new applications & Day 2 Products)</p>	<p>Pre & Post Launch Sensor Calibration and Validation</p>	<p>Operational Algorithm Readiness Development and Transition to Operations</p>	<p>Sustained Post Launch Validation and Reactive Science Maintenance</p>	<p>Proving Grounds and User Readiness</p>
<p>Risk Reduction</p>	<p>GOES-R Calibration Team <i>(AWG is a team member)</i></p>	<p><i>Algorithm Working Group</i> <i>Algorithm Working Group</i></p>		<p>Proving Ground & Risk Reduction</p>

Key components of a successful satellite program
Established GOES-R programs/activities and working groups that directly support these components



AWG Teams



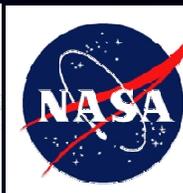
GOES-R Products are Mapped to AWG Product Application Teams

AWG Product Application Teams	Team Lead
Imagery	Tim Schmit
Soundings	Tim Schmit
Winds	Jaime Daniels
Clouds	Andrew Heidinger
Aviation	Ken Pryor, Wayne Feltz
Hydrology	Robert Kuligowski
Land	Bob Yu
Cryosphere	Jeff Key
Radiation Budget	Istvan Lazslo
Lightning	Bill Koshak
SST	Alexander Ignatov
Ocean Dynamics	Eileen Maturi
Aerosols/Air Quality/Atmos. Chemistry	Shobha Kondragunta
AWG Specialty Teams	Team Lead
Proxy Data	Fuzhong Weng
Cal/Val (Sensor)	Changyong Cao
Algorithm Integration	Walter Wolf



AWG Algorithm Development Scope

Develop algorithms for the following L2 products...



BASELINE Products

OPTION-2 Products

Advanced Baseline Imager (ABI)

GLM

- **Clouds and Moisture Imagery (KPP)**
- Clear Sky Mask
- Cloud Top Pressure and Height
- Cloud Top Phase
- Cloud Top Temperature
- Cloud Particle Size Distribution
- Cloud Optical Path
- Temperature and Moisture Profiles
- Total Precipitable Water
- Stability Parameters (Lifted Index)
- Aerosol Detection
- Aerosols Optical Depth
- Derived Motion Winds
- Hurricane Intensity
- Fire/Hot Spot Characterization
- Land and Sea Surface Temperature
- Volcanic Ash
- Rainfall Rate
- Snow Cover
- Downward Solar Insolation: Surface
- Reflected Solar Insolation: TOA
- Lightning Detection

- Cloud Layer/Heights
- Cloud Ice Water Path
- Cloud Liquid Water
- Cloud Type
- Convective Initiation
- Turbulence
- Low Cloud and Fog
- Enhanced "V"/Overshooting Top
- Aircraft Icing Threat
- SO₂ Detections (Volcanoes)
- Visibility
- Upward Longwave Radiation (TOA)
- Downward Longwave Radiation (SFC)
- Upward Longwave Radiation (SFC)
- Total Ozone
- Aerosol Particle Size
- Surface Emissivity
- Surface Albedo
- Vegetation Index
- Vegetation Fraction
- Flood Standing Water
- Rainfall probability and potential
- Snow Depth
- Ice Cover
- Sea & Lake Ice Concentration, Age, Extent, Motion
- Ocean Currents, Currents: Offshore



AWG Teams



- Product Application Teams
- Proxy Data Team
- Algorithm Integration Team
- Cal/Val (sensor) Team



AWG Roles & Responsibilities

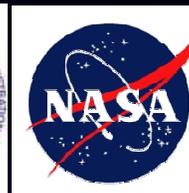


- Develop all Level-2 product algorithms  ***Product Application Team Role***
- Acquire/develop proxy data for algorithm development & testing  ***Product Application and Proxy Team Roles***
- Perform Level-2 product Cal/Val  ***Product Application Team Role***
- Ensure GOES-R L1b integrity  ***Cal/Val (sensor) Team Role***
- Lead cross sub-team activities  ***Algorithm Integration Team Role***



AWG Algorithm Integration Team

Roles & Responsibilities...



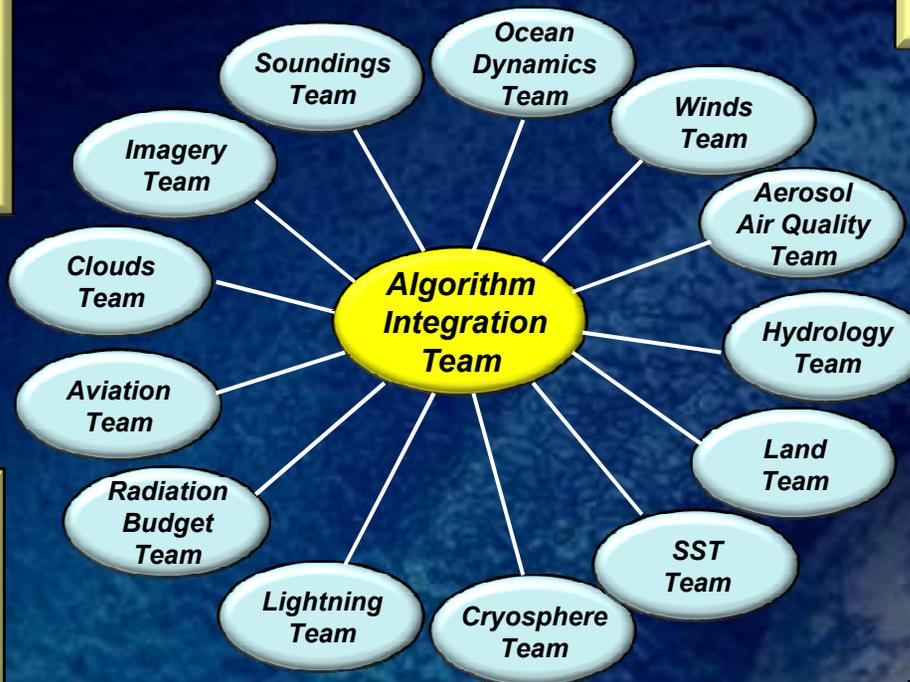
Manage Processes

- Initial Requirements Analysis
- Algorithm Design Review
- Critical Design Review
- Test Readiness Review
- Code Unit Test Review
- Algorithm Readiness Review
- Software CM



Enforce Standards

- Algorithm Theoretical Basis Document
- Metadata (FGDC guidelines)
- Interface Control
- System Description
- Users Manual
- Fortran Programming
- C/C++ Programming
- Test Plan
- Algorithm Implementation Instructions
- Latency Reports



Coordinate Algorithm Development & Integration Activities

Develop and Maintain Algorithm Framework and Testbed

Integrates algorithm software from the product application teams

AWG Focal Point for interactions between AWG, GOES-R Ground Segment, and Harris/AER



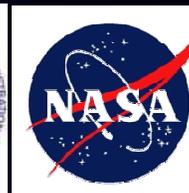
AWG Current Efforts in GOES-R ABI Level-2 Algorithm Development and Validation

- *Algorithm Development and Validation Strategies*
- *Proxy and Validation Data Sources*
- *Status of AWG Deliverables*
- *Product Examples*



Algorithm Development Strategy

A wide variety of instrument proxy datasets have been assembled and are being used...



"Real" ABI PROXY Data Sources

"Simulated" ABI Proxy Data Sources

Meteosat/
SEVIRI

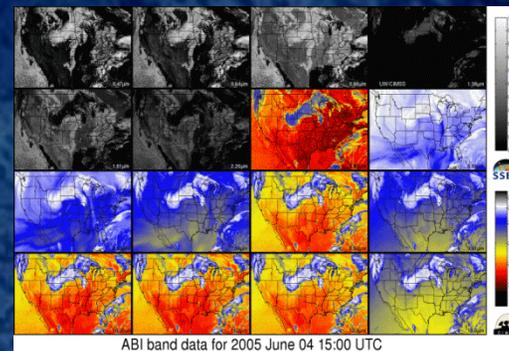
Current GOES



AVHRR



(FD, CONUS, Meso)



ABI band data for 2005 June 04 15:00 UTC

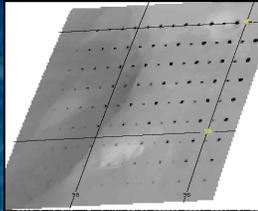
MODIS



TRMM/LIS



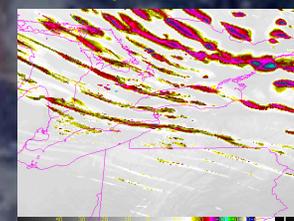
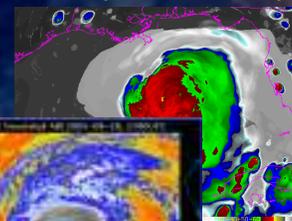
3.9um (for fires)



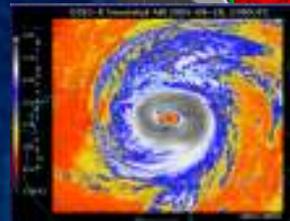
Case Studies

10.35um (Hurricane Lili)

10.35um (Lake Effect Snow)



11.2 um (Hurricane Katrina)



AWG Proxy and Product Application Teams have assembled a wide variety of instrument proxy and simulated datasets to use for algorithm development, testing, and validation activities



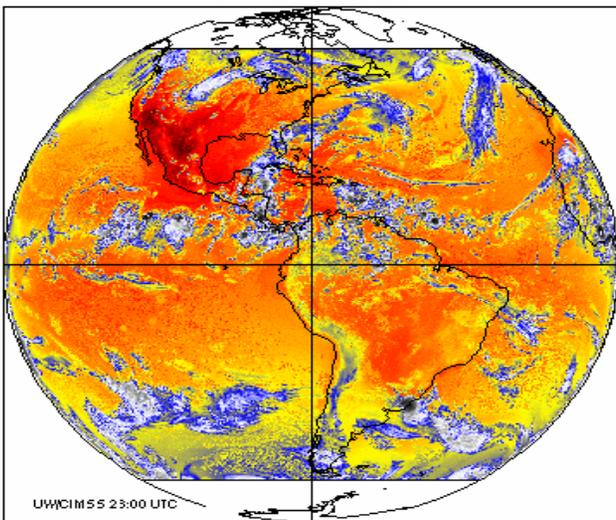
GOES-R ABI Proxy Datasets

From the AWG Proxy Team at CIMSS...



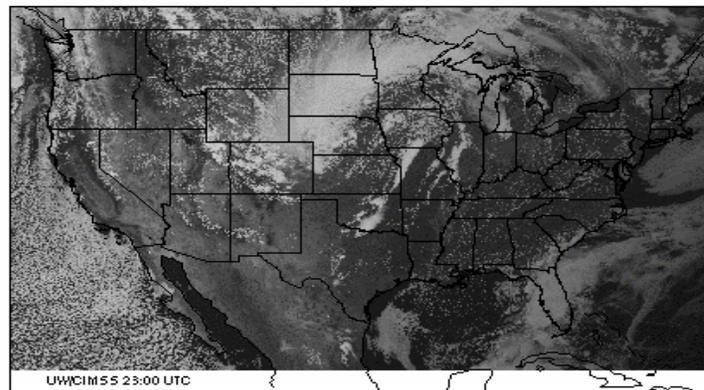
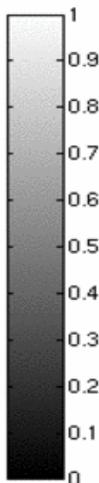
15 minutes of ABI

ABI band 14 (11.2 μm) BT (K) 2005-06-04

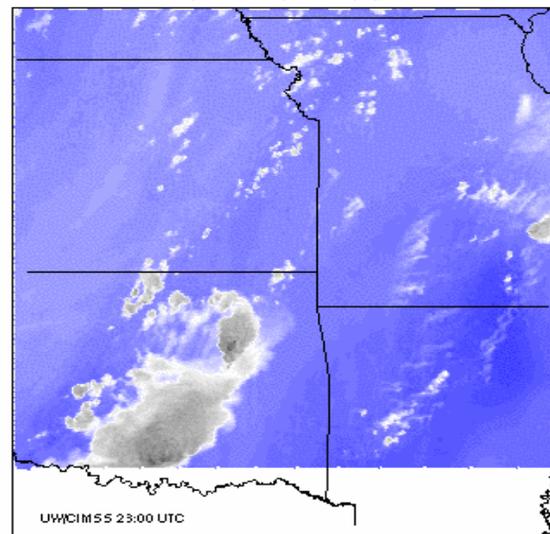
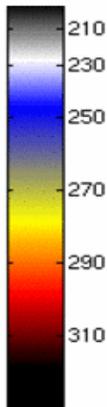


June 4, 2005 23:00 UTC

ABI band 2 (0.64 μm) reflectance 2005-06-04



ABI band 8 (6.19 μm) BT (K) 2005-06-04

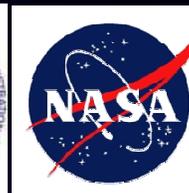


These high fidelity simulated datasets are important for algorithm development and validation activities



GOES-R ABI Proxy Datasets

From the AWG Proxy Team at CIRA...

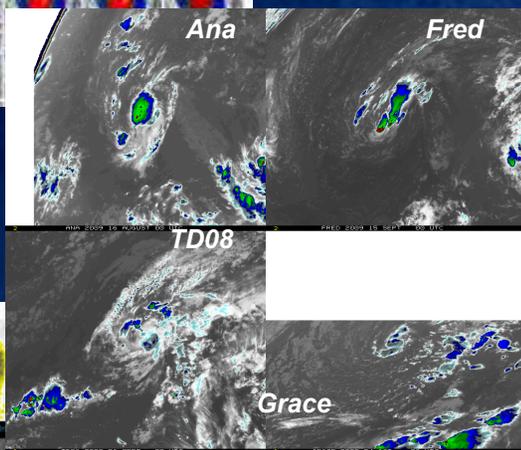
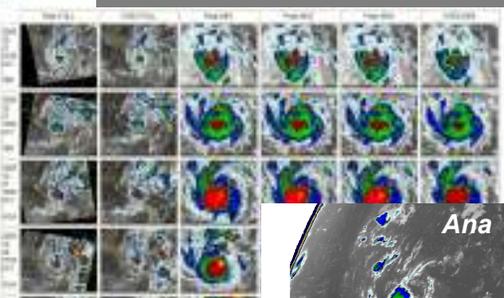


Tropical Storm Proxy Datasets

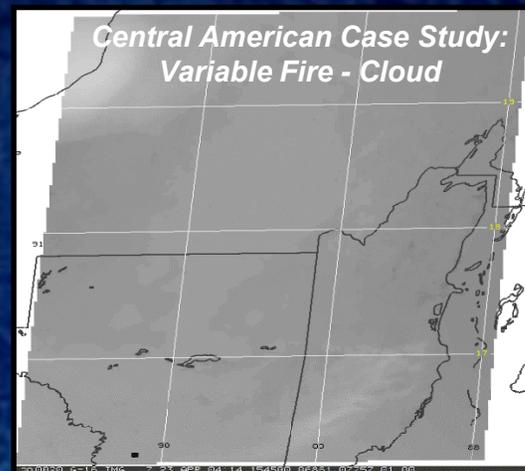
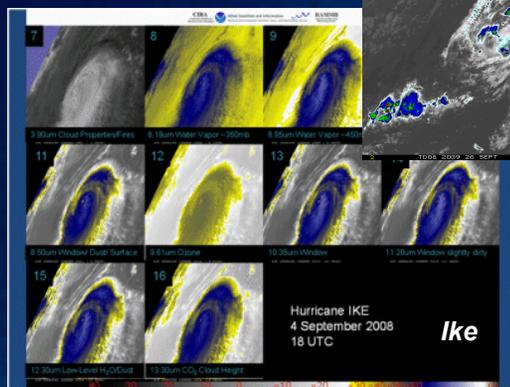
Fire/Hot Spot Datasets



AVHRR, MODIS, GOES-12 data collection for 11 tropical storms over the period 2002-2006



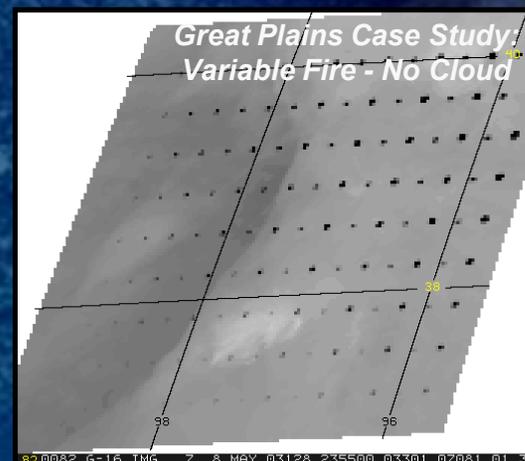
Synthetic ABI imagery for a number of tropical cyclone cases



Simulated ABI 3.9 μm band with prescribed fires/hot spots inserted

Simulation Scenarios:

- constant fire/no cloud
- constant fire/with cloud
- variable fire/no cloud

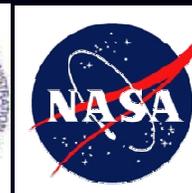


These specialized ABI proxy datasets are important for algorithm development and validation activities

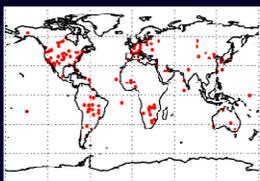


Algorithm Validation Strategy

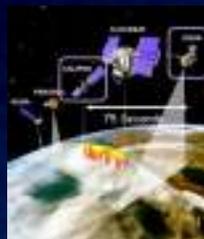
A wide variety of reference ("Ground Truth") datasets have been assembled and are being used...



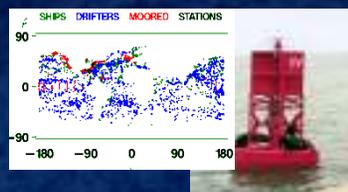
Aeronet Stations Aerosol Optical Depth



CALIPSO, CLOUDSAT Clouds, Icing



Bouys, Ships SST



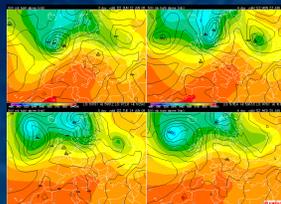
SURFRAD, ARM LST, Radiation



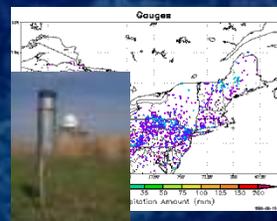
Radiosondes Winds, Temperature, Moisture, Stability



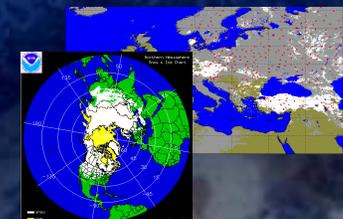
NWP Analyses Winds, Temperature, Moisture



Rain Gauges Precipitation



Sfc Snow Reports, NESDIS IMS Snow



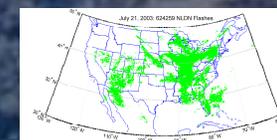
Ground-based Ozone Ozone



Pilot Reports Icing, Turbulence



National Lightning Detection Network (NLDN) Lightning

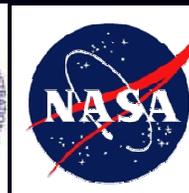


AWG Product Application Teams and the Proxy Data Team have assembled a wide variety of "Ground Truth" datasets to use for Level-2 product validation activities



Algorithm Development and Validation Strategies

An iterative process...



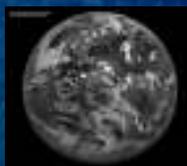
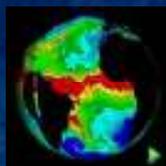
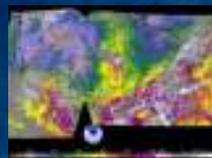
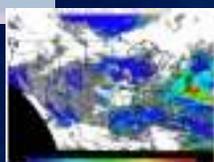
Algorithm Iterations



Seasonal conditions represented



Wide variety of atmospheric and surface conditions are represented



Level 2 Product Generation

Validate with Ground Truth

MORE IS BETTER!

As algorithms mature...

- ✓ Better estimates of product performance
- ✓ Increased confidence that on-orbit product performance will meet specs
- ✓ Increased confidence that user needs are met

AWG is responsible for Level-2 product accuracy and precision specifications, and has therefore, worked to establish robust pre-launch validation strategies for each product

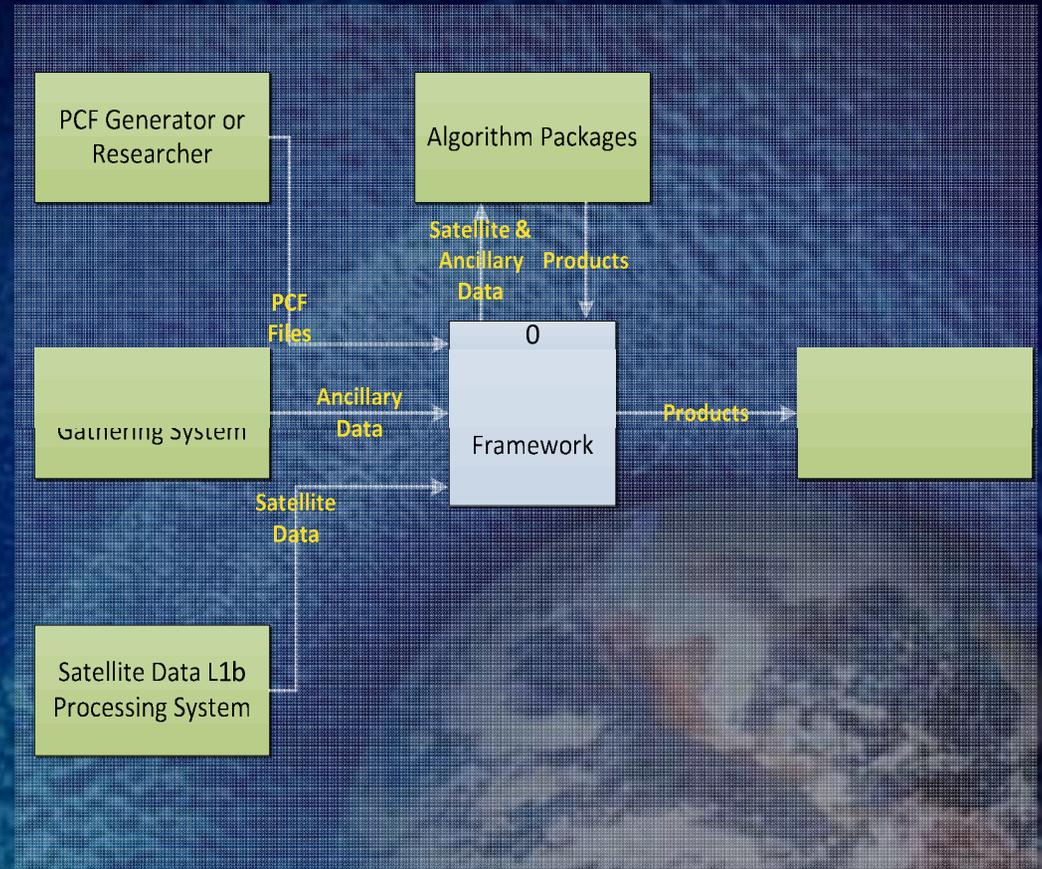


AWG Algorithm Framework

Developed by the AWG Algorithm Integration Team...



- Test bed for AWG algorithm development and performance testing
 - Enables testing of code, algorithm integration, compilers, use of common ancillary data and forward models
 - Enables algorithm chaining (ie., product algorithm precedences)
- Used for verification of Level-2 algorithm performance (accuracy & precision specifications) and output
 - For long-term, common proxy datasets
 - SEVIRI and MODIS
 - 10 and 16 week proxy datasets covering all seasons
 - Special datasets





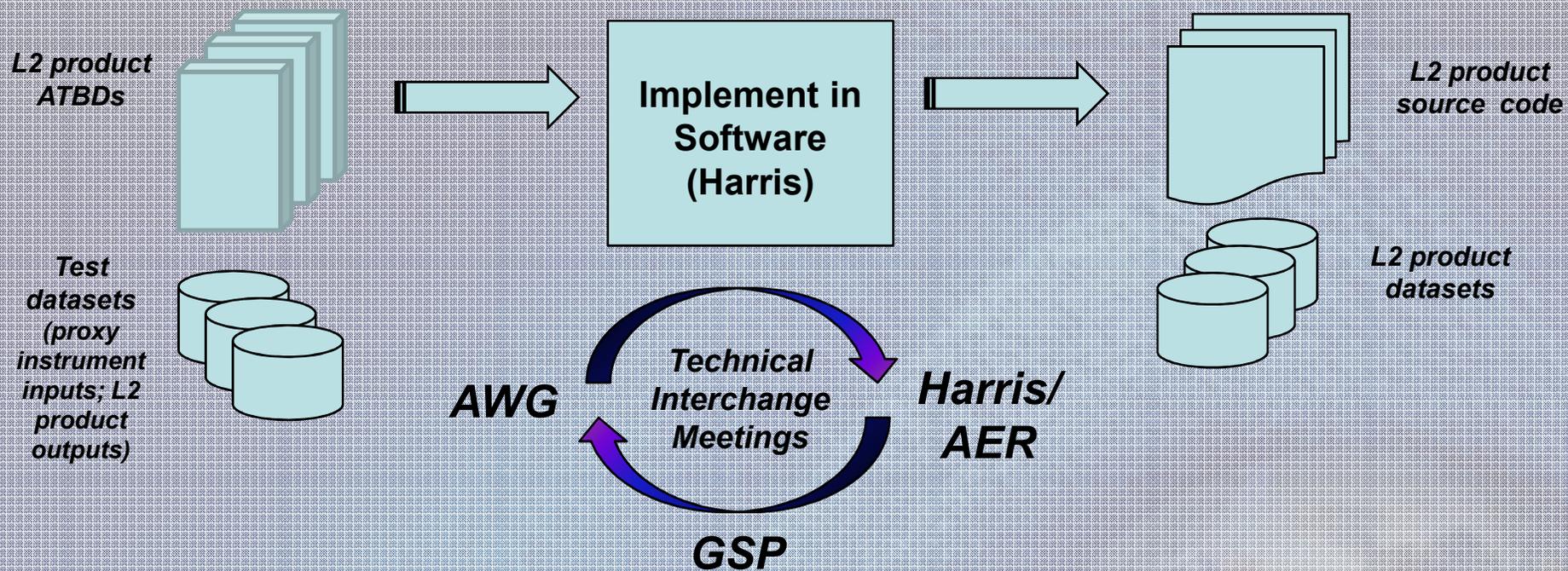
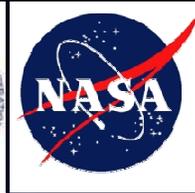
Status of AWG Deliverables to the GOES-R Ground Segment



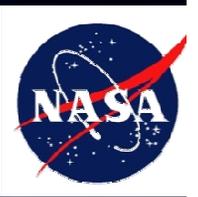
- **Algorithm Packages (APs)**
 - Algorithm Theoretical Basis Documents (ATBD)
 - Instrument proxy datasets
 - Product output datasets (for reproducibility)
 - Algorithm Interfaces and Ancillary Data Description (AIADD) document
- **Schedule of Deliveries to the GOES-R Program**
 - ✓ September 2008: As-Is ATBDs (Baseline & Option 2)
 - ✓ September 2009: 80% APs for Baseline Products
 - ✓ November 2010: 100% APs for Baseline Products
80% APs for Option 2 Products
 - September 2011: 100% APs for Option 2 Products



From ATBDs to Level-2 Product Software



- **AWG** is currently working closely with **Harris/AER** and the **GOES-R Ground Segment Project (GSP)** and **Harris/AER** in support of Harris' implementation of **GOES-R Level-2 product algorithms**
 - ❑ Process is critical for proper implementation of the L2 product algorithms
 - ❑ Process is key for Harris to meet the reproducibility requirement (GSFPS-2758)



GOES-R Level-2 Product Examples



Cloud Height

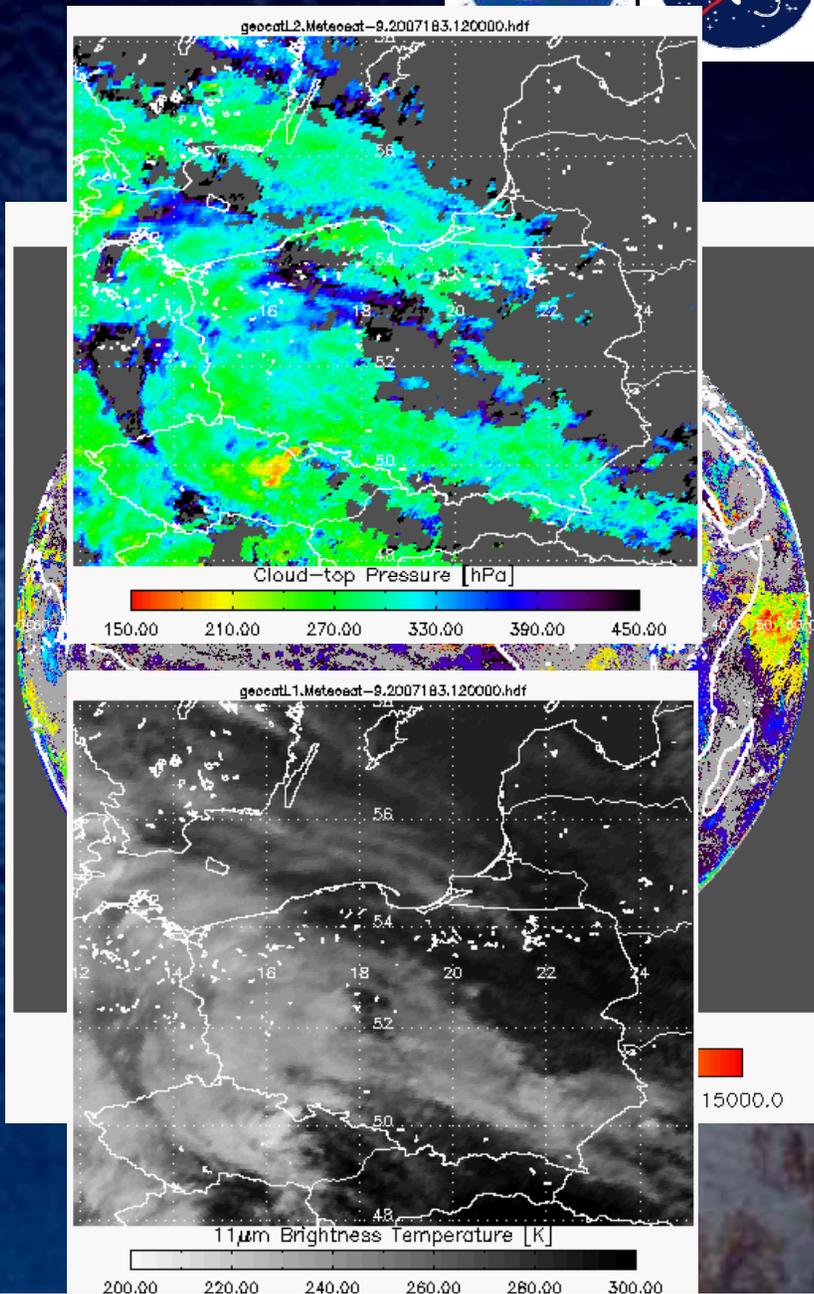


- **Algorithm Highlights**

- Algorithm uses the 11, 12 and 13.3 μ m channels to estimate cloud temperature, cloud emissivity and a cloud microphysics.
- Algorithm uses an optimal estimation approach that provides error estimates.
- Cloud pressure and height are computed from NWP profiles.
- For multi-layer clouds, lower cloud height estimates obtained from surrounding pixels.
- Cloud heights in the presence of low level inversions are handled using similar logic that is employed in the MODIS algorithms.

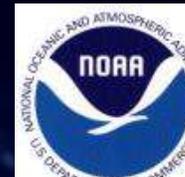
- **Operational Applications**

- Aviation Terminal Aerodrome Forecasts (TAFs)
- Supplements Automated Surface Observing System (ASOS) with upper-level cloud information
- Cloud initialization
- Assimilation into NWP models





Temperature & Moisture Soundings, Precipitable Water, Atmospheric Stability Products



Algorithm Highlights

- 1D-variational physical retrieval algorithm that has heritage with MODIS and current operational GOES sounder physical retrieval algorithms
- Regression-based initial guess T/Q profiles
- Utilizes NWP forecast T/Q profiles
- Utilizes the 6.15, 7.0, 7.4, 8.5, 9.7, 10.35, 11.2, 12.3, and 13.3 μm bands)
- Exploits recent improvements in fast clear-sky radiative transfer models and ancillary data (surface emissivity)

Operational Applications

Nowcasting

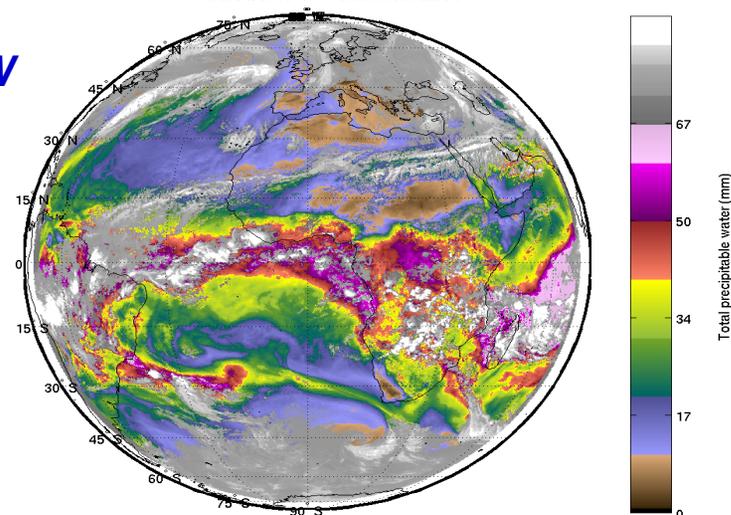
- Gulf of Mexico return flow
- Southwest US monsoon
- QPF (heavy rain, flash flooding)
- Convective potential and morphology
- Fog potential
- Situational awareness in pre-convective environments for potential watch/warning scenarios

NWP

- Assimilation into regional and mesoscale NWP models (TPW)

SEVIRI TPW--2006045:12:00

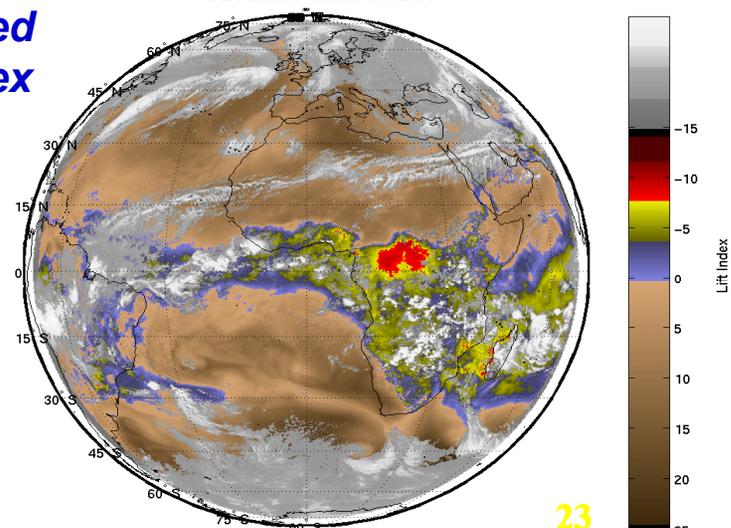
TPW



UW/CIMSS (Jin & Li, 2007)

SEVIRI LI--2006045:12:00

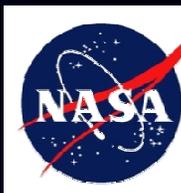
Lifted Index



23
UW/CIMSS (Jin & Li, 2007)



Rainfall Rate/QPE



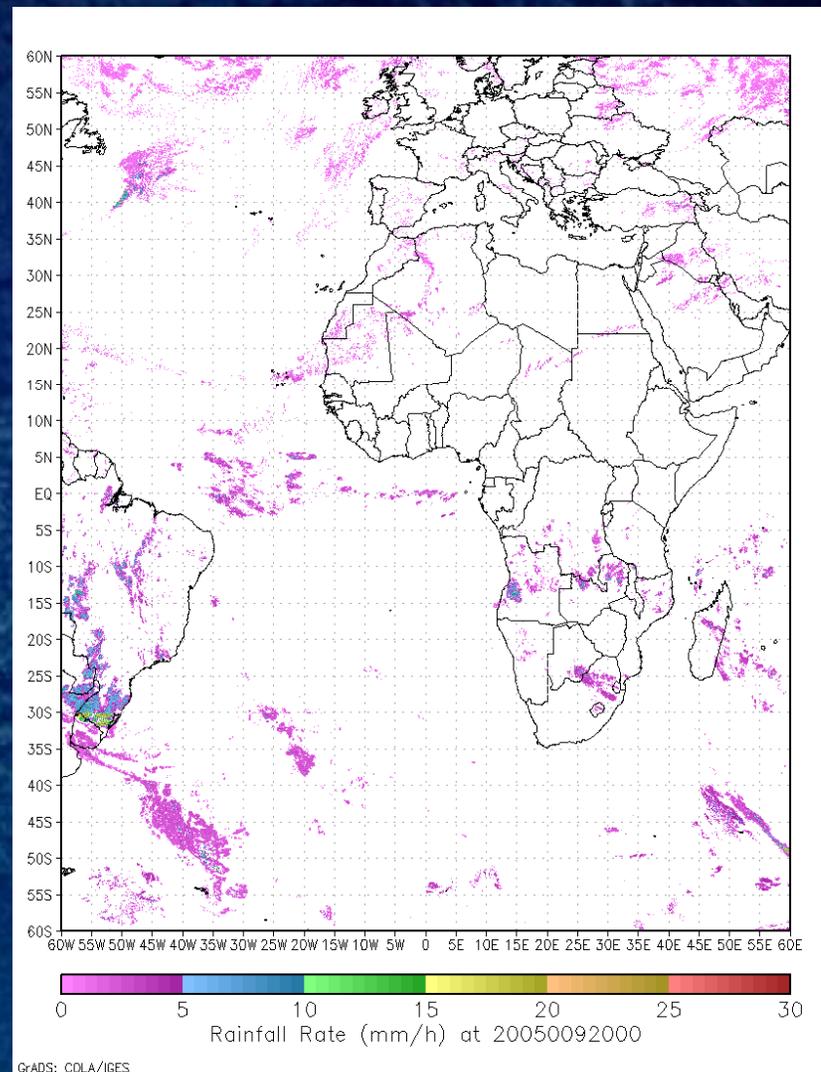
Rainfall rate derived from Meteosat-8 SEVIRI
2000 UTC on 09 January 2005

Algorithm Highlights

- Self-Calibrating Multivariate Precipitation (SCaMPR) retrieval algorithm
- VIS/IR-based algorithm that is dynamically calibrated against satellite-based microwave (MW) derived rain rates (SSM/I, AMSU, AMSR-E and TRMM)
- Calibration is continuously updated to reflect time changes in MW-IR relationship
- Dynamic channel selection
- Leverages ABI's higher spatial and temporal resolution data

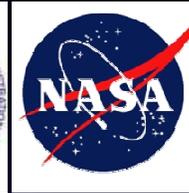
Operational Applications

- Flash flood forecasting
- Nowcasting
- Assimilation into hydrologic models

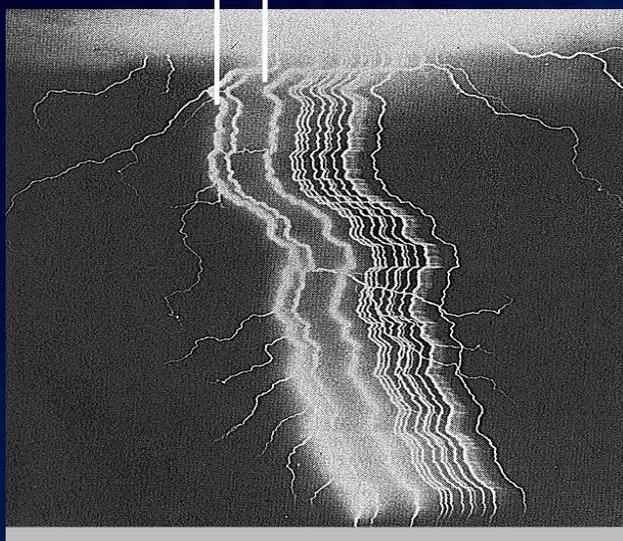




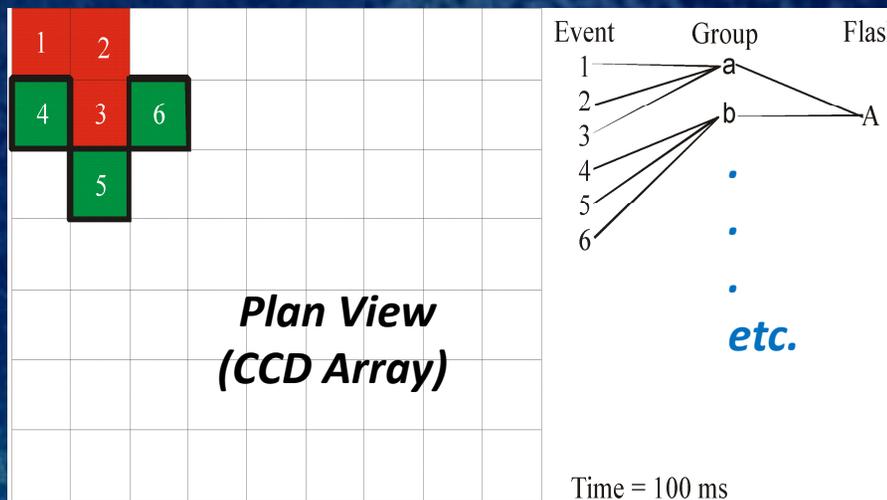
GLM Lightning Product



Group a
Group b
••• etc.



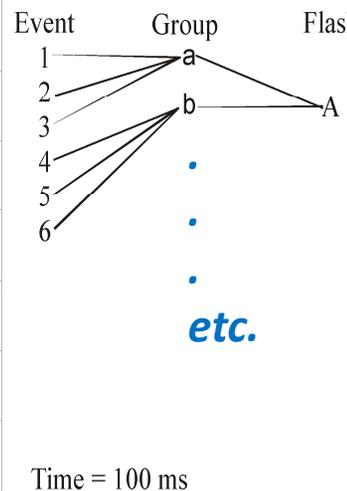
Groups Help Track Strokes & other components of the flash.



Altitude

time →

Plan View
(CCD Array)

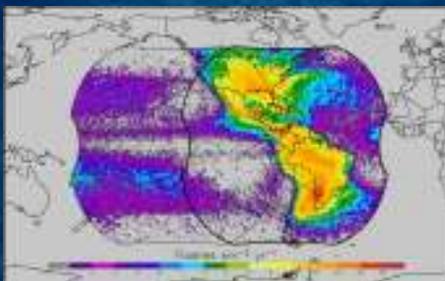


Event: The occurrence of a single pixel exceeding the background threshold during a single frame

Group: Two or more adjacent events in the same time frame

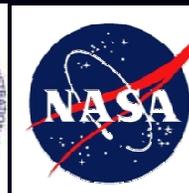
Flash: A set of groups sequentially separated in time by no more than 330 ms and in space by no more than 16.5 km

GLM
FOV²⁵
(1372 x 1300)





Derived Motion Winds



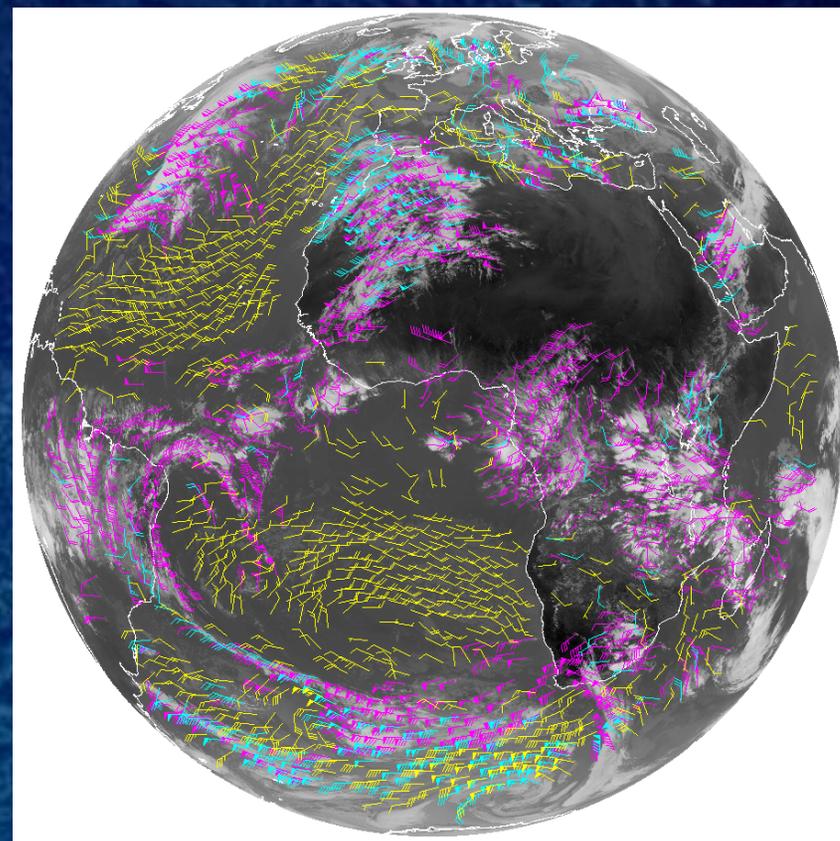
• Algorithm Highlights

- Heritage in targeting, tracking, and QC algorithms lie with current NESDIS operational winds algorithms
- New nested tracking algorithm introduced that makes use of a two-dimensional clustering algorithm to capture the dominant motion in each target scene
- Utilizes clear sky mask product
- Wind height assignment will rely on utilization of pixel level cloud heights generated upstream via algorithms delivered by AWG cloud application team
- Leverages ABI's higher spatial and temporal resolution data

• Operational Applications

- Weather Forecasting
- Assimilation into mesoscale and global NWP models
- Aviation (flight routing)

Cloud-drift Winds derived from a Full Disk Meteosat-8 SEVERI 10.8 μm image triplet centered at 1200 UTC 01 February 2007

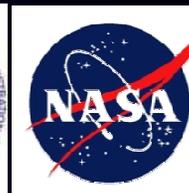


High Level 100-399 mb Mid-Level 400-699 mb Low-Level >700 mb

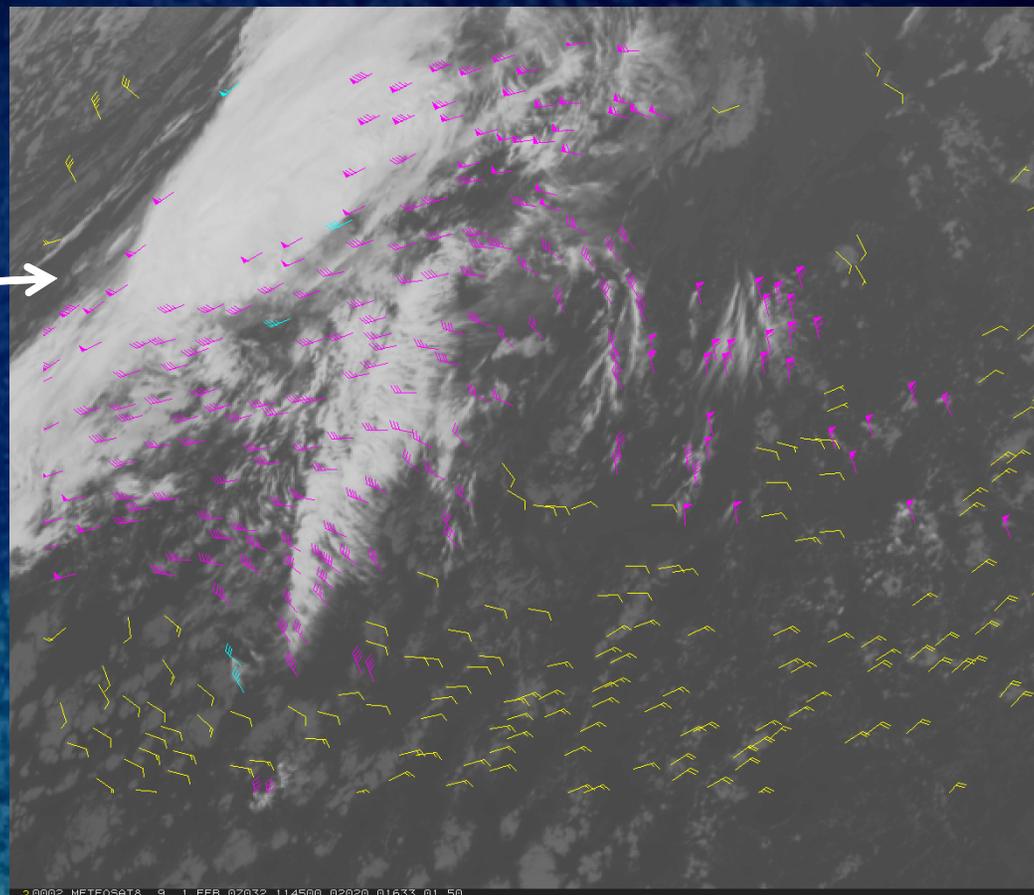
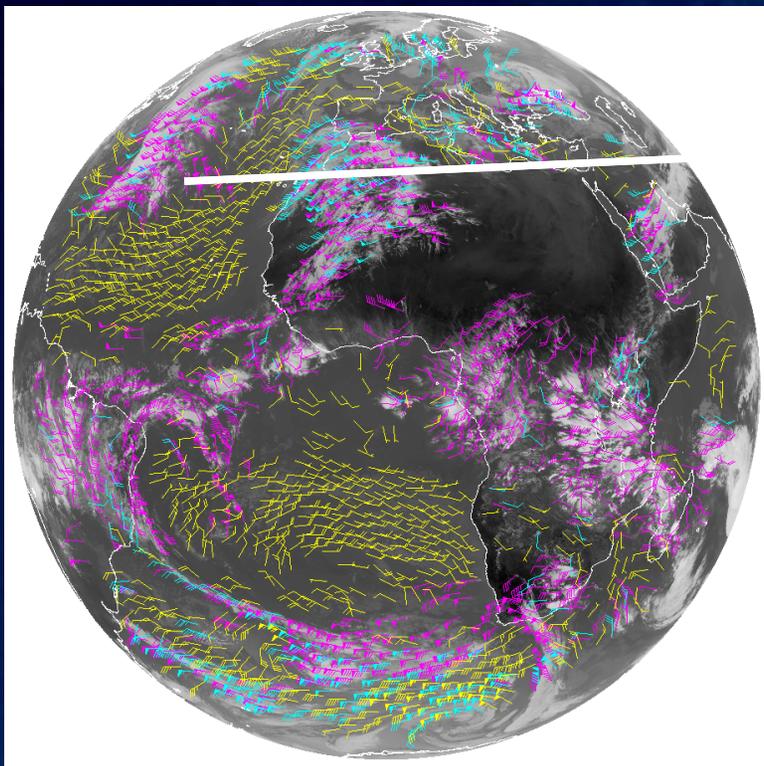


Derived Motion Winds

Long-wave IR Cloud-drift Winds



Cloud-drift Winds derived from a Full Disk
Meteosat-8 SEVERI 10.8 μm image triplet
centered at 1200 UTC 01 February 2007



20002 METEOSAT8 9 1 FEB 07032 114500 02020 01633 01 50

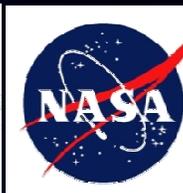
High-Level 100-400 mb

Mid-Level 400-700 mb

Low-Level >700 mb

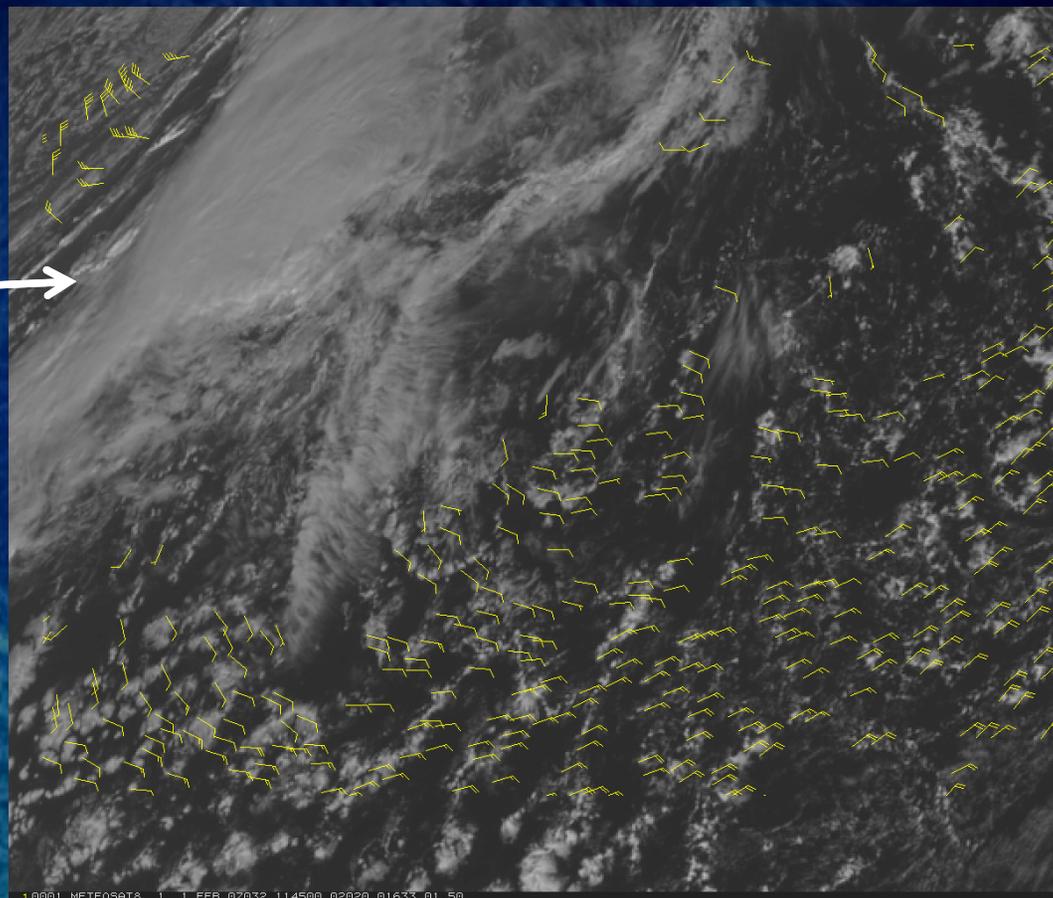
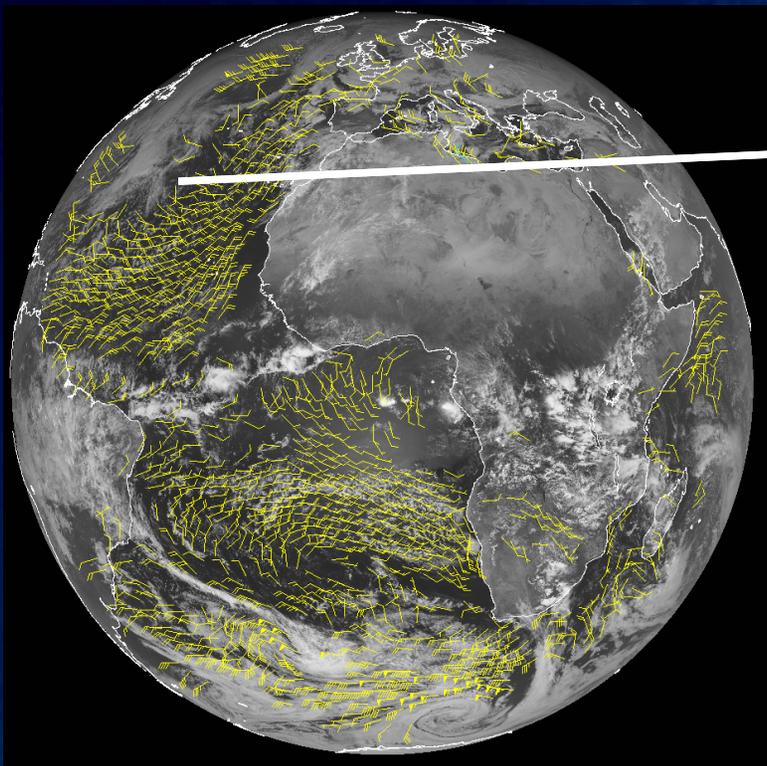


Derived Motion Winds



Visible Cloud-drift Winds

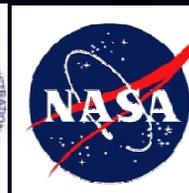
Cloud-drift Winds derived from a Full Disk
Meteosat-8 SEVERI 0.60 μm image triplet
centered at 1200 UTC 01 February 2007



Low-Level >700 mb



Fire/Hot Spot Characterization



Algorithm Highlights

- Heritage lies with the GOES operational Wildfire Automated Biomass Burning Algorithm (WF_ABBA)
- Dynamic, multi-spectral, thresholding contextual algorithm
- Utilizes the 0.64, 3.9, 11.2 and 12.3 μm channels
- Leverages ABI's higher spatial and temporal resolution data

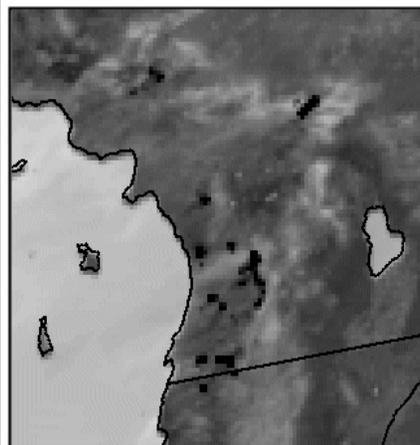
Operational Applications

- Fire weather forecasting
- Air quality forecasting

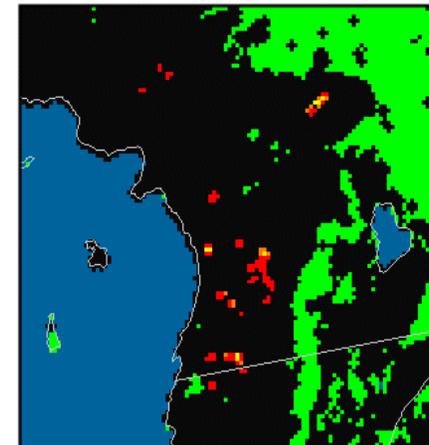
MODIS Simulated ABI Data in Southern California

Date: 23 October 2007

Time: 18:25 UTC



GOES-R ABI 3.9 μm data



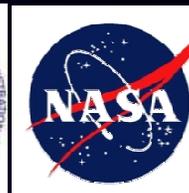
CIMSS GOES-R ABI WF_ABBA Fire Mask Product

Experimental Wildfire ABBA Fire Legend

Processed Fire	Saturated Pixel	Cloudy Fire	Biome Block-out Zone
High Possibility Fire	Medium Possibility Fire	No background	Solar Block-out Zone



Land Surface Temperature

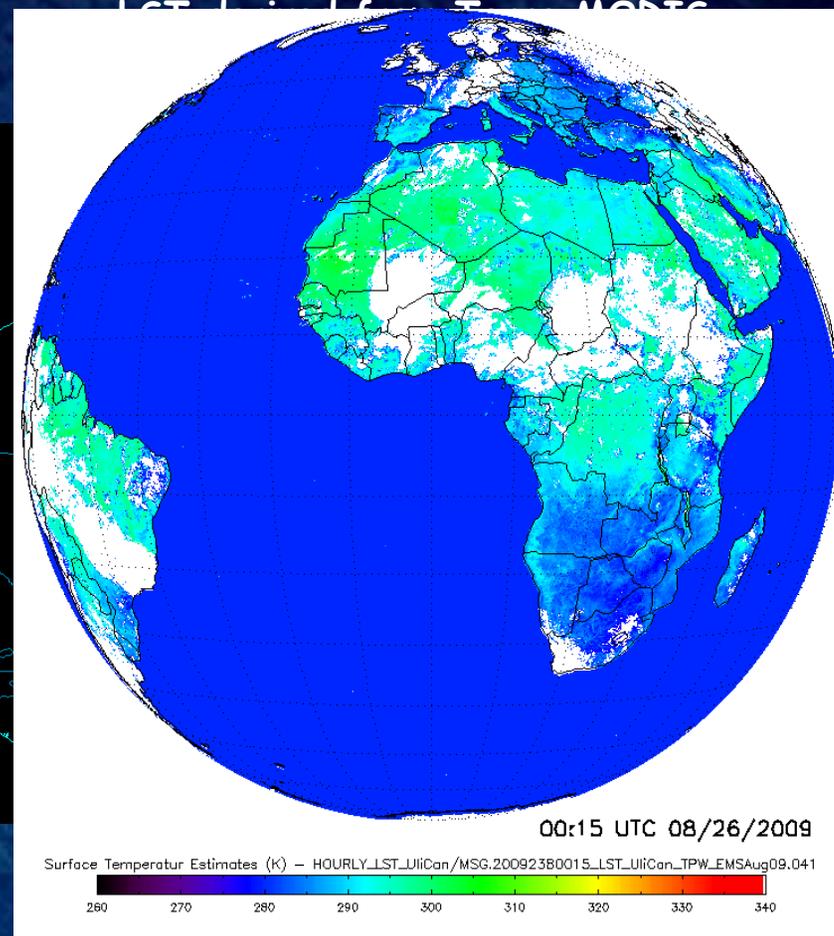


• Algorithm Highlights

- Utilizes ABI clear sky mask product
- Regression-based algorithm that uses the 11.2 and 12.3 μm channels
- Split-window algorithm has significant heritage (geo & leo)
- Leverages ABI's higher spatial resolution data

• Operational Applications

- Fog forecasting
- Frost/freezing temperature forecasting
- Assimilation into land surface models
- Assimilation into mesoscale and climate NWP models
- Climate prediction





Snow Cover



Algorithm Highlights

- Retrieves sub-pixel fractional snow cover and grain size estimates via computationally efficient spectral mixture modeling
- Heritage derived from
 - MEMSCAG (Multiple Endmember Snow Covered Area and Grain size) algorithm for imaging spectrometers (AVIRIS, Hyperion, HYDICE, ARTEMIS)
 - MODIS-based fractional snow cover and grain size (MODSCAG) algorithm
- Leverages ABI's higher temporal resolution data and spectral coverage (VIS/near IR bands :0.47, 0.64, 0.86, 1.6, and 2.25 μm)

Operational Applications

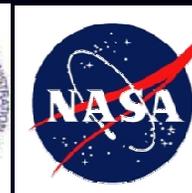
- Assimilation into NOAA/NOHRC snow model
- Hydrologic forecasts and warnings, including river and flood forecasts
- Stream-flow forecasting/modeling
- Snowpack monitoring, analysis
- Water management
- Climate studies

MODIS Color Composite (Colorado Rockies)
30 April 2007





Volcanic Ash



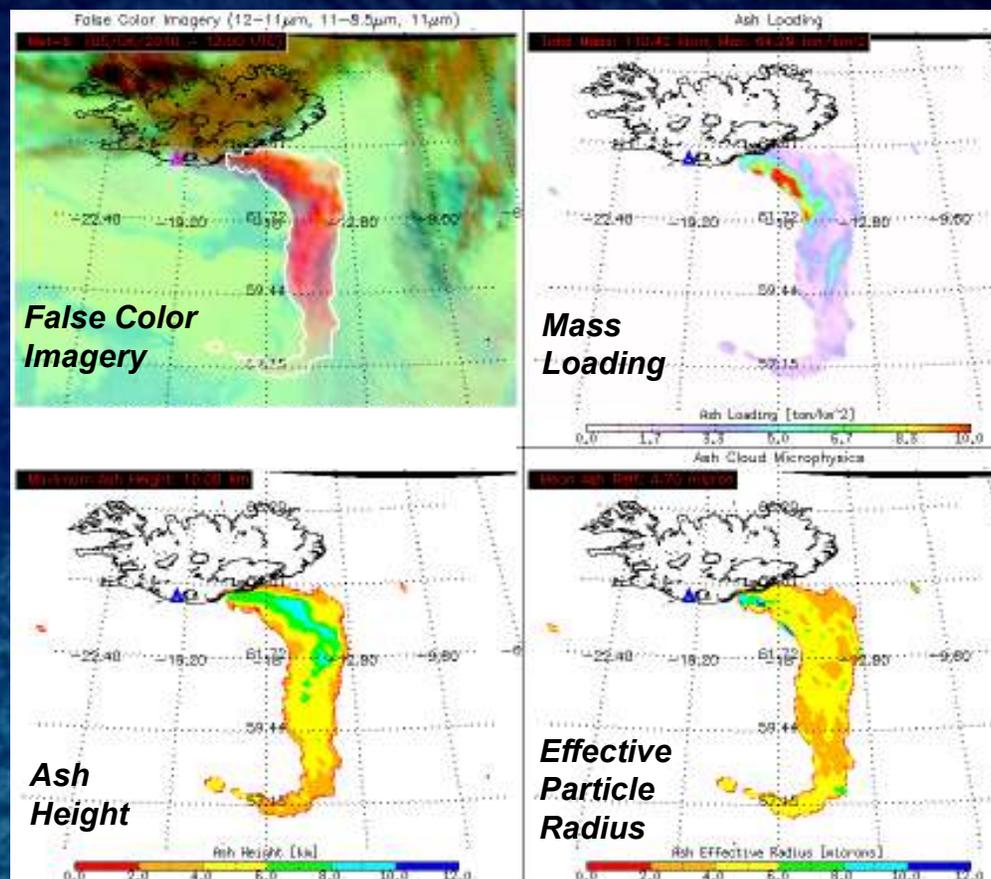
Iceland's Eyjafjallajökull Volcano

Algorithm Highlights

- Detects volcanic ash and estimates its height and mass loading
- Leverages the new ABI 8.5 μm band, The 8.5 μm , 11.2 μm , and 12.3, 11.2 μm channel pairs are used to detect volcanic ash
- An optimal estimation approach is used to estimate ash cloud temperature, emissivity and microphysical index.
- Ash cloud height determined from NWP profiles.
- Mass loading estimated from computed optical depth and effective particle size
- Leverages ABI's new 8.5 μm channel, along with 11.2 μm and 12.3 μm for sensitivity to cloud microphysics (including composition)

Operational Applications

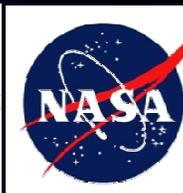
- Aviation safety
- Health safety
- Climate studies



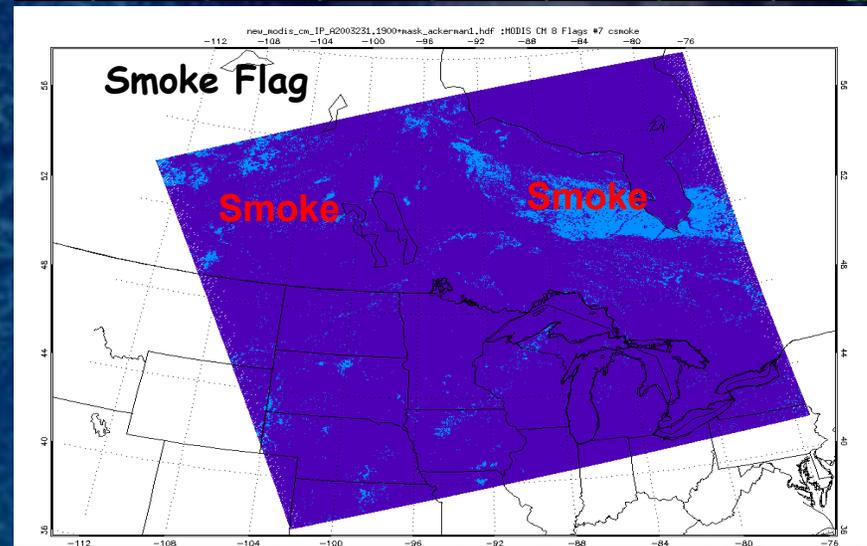


Aerosol Detection

(Smoke & Dust Detection)



MODIS Color Composite (British Columbia, Canada Fire Event) 19 August 2003



Algorithm Highlights

- Spectral threshold algorithm that uses spectral (wavelength dependent) characteristics of surface, aerosols, and clouds to identify aerosols
- Heritage derived from AVHRR and MODIS-based aerosol detection algorithms
- Synergy with VIIRS aerosol retrieval algorithm
- Leverages ABI's higher spectral (VIS/near IR portion) coverage data

Operational Applications

- Air quality forecasting
- Air quality assessment and management
- Climate studies



Level-2 Product Calibration/Validation

- *Guiding Principles*
- *Importance of Validation*
- *Objectives*
- *Strategies*
- *Cal/Val Phases/Timelines*
- *AWG Role in Cal/Val*

Putting the pieces together for a successful GOES-R Cal/Val Program...



Calibration/Validation

Guiding Principles...



- 1) **Sensor Performance and Characterization** are the cornerstone of all data products.
- 2) **Experience and resources from Past and Current Operational and Science Missions** should be fully exploited and incorporated in the GOES-R Cal/Val Program.
- 3) **Customer and User Satisfaction is achieved through participation in the Cal/Val process.**
- 4) **User community Proficiency with Operational Algorithms and products are essential to efficient Cal/Val, user community buy-in, and user readiness.**
- 5) **Space-borne assets, Global models, Surface Networks and Data Assimilation** provide a cost effective comprehensive first view of sensor and algorithms performances.
- 6) **Targeted Campaigns and Special Studies** should be planned and executed as needed.
- 7) **Plan for Level-2 Product algorithm tuning and corrective actions during the post-launch period.**

(From Heather Kilcoyne, SPIE 2009 presentation on NPP Cal/Val)



What is Validation?



Validation:

The process of determining that the deliverable item satisfies its intended use in its intended environment.

- *GOES-R Program Acronym and Glossary*

The process of assessing, by independent means, the quality of the data products derived from the system outputs. [For example, assessing a derived L2 product against similar Reference/"Ground Truth" observations obtained from some other observing system (ground-based, satellite, NWP).]

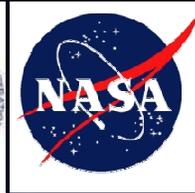
- *Committee on Earth Observation Satellites*

Sections 3.3.3.1- 8; 3.3.4.1-7; 3.3.5.1-3 of the GOES-R Mission Requirements Document (MRD) provide requirements for L2 product geographic coverage, vertical resolution, measurement range, accuracy, precision, refresh rate, latency, and qualifiers.

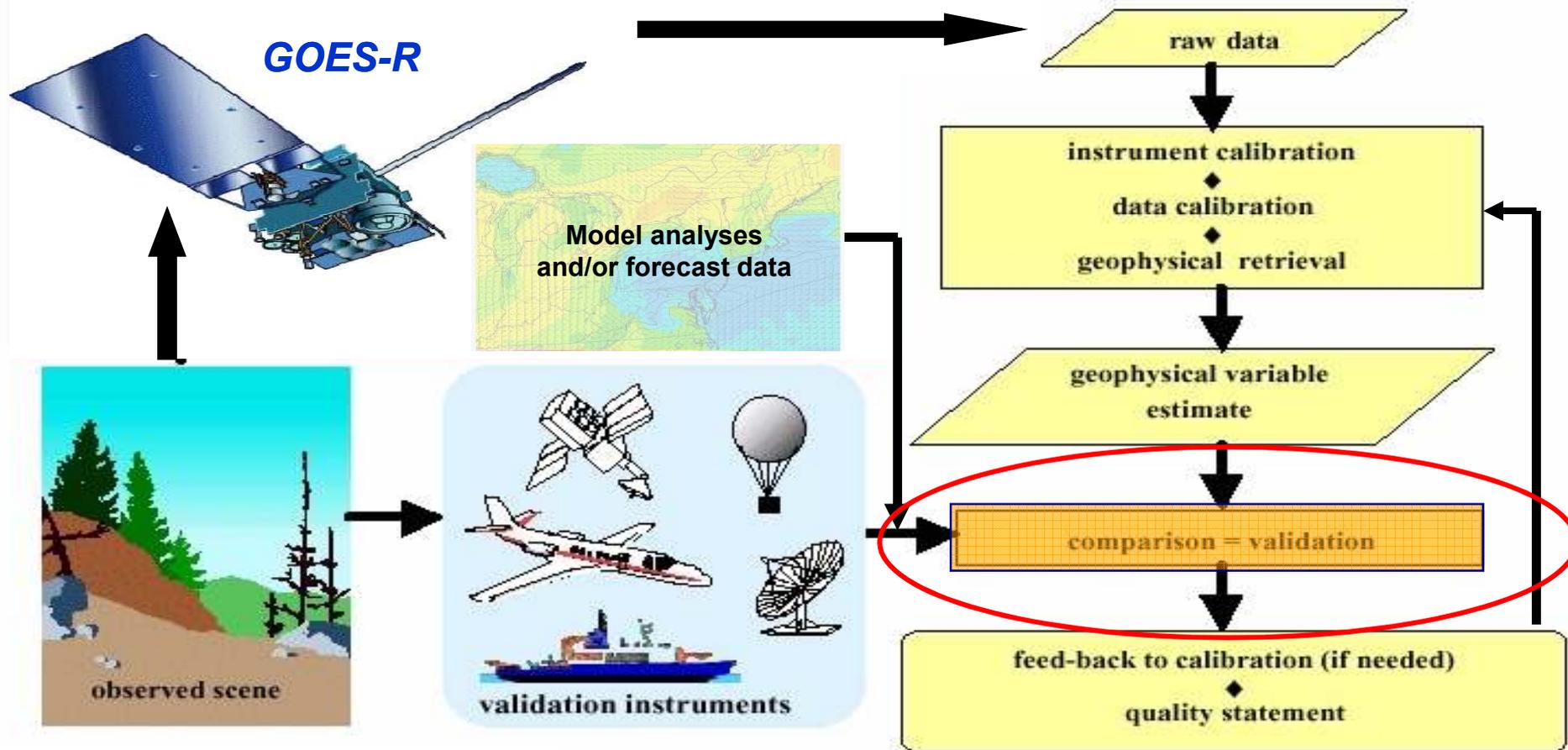
Section 4.1 of the MRD provides requirements for the validation of all GOES-R derived products pre-launch, post-launch, and throughout the mission.



What is Validation?



Validation is the process of assessing by independent means the quality of the data products derived from the system outputs





Product Calibration/Validation *Objectives...*



- **Characterize performance of** GOES-R Level-2 products and **demonstrate** that they meet their respective specification requirements as described in the GOES-R Requirement Documents
 - Level-1 Requirements Document (L1RD)
 - Mission Requirements Document (MRD)
 - Functional & Performance Specification (F&PS) document
- **Provide the GOES-R user community with operationally viable, validated, and useful data products for their applications and missions**
- Provide investigations into any product issues that impact a customer's ability to fulfill their missions and provide effective solutions



Product Calibration/Validation Strategies...

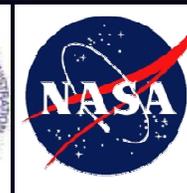


- Build the necessary infrastructure and leverage existing infrastructures
 - Hardware/Network
 - Compute & data storage facilities
 - Data
 - Instrument datasets (**proxy data followed by real data**)
 - “Ground truth”/Reference datasets
 - Level-2 product algorithms
 - Level-2 product processing capability
 - Cal/Val tools for Collocation, Data Analysis, and Visualization
- Build the necessary collaborations
 - Research community
 - User community
 - Operational data providers

Strategies that enable the execution of all GOES-R Level-2 product validation activities from pre-launch through the post-launch phases of the GOES-R Program

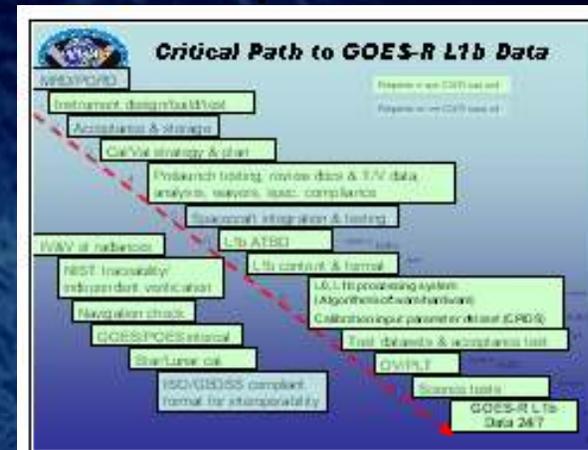


The Four Phases of Cal/Val



Critical path Identified

- Pre-Launch
- Early check-out and Post-Launch Tests (PLT)
- On-orbit verification (OV) & Intensive Cal/Val (ICV)
- Long-Term Monitoring (LTM)

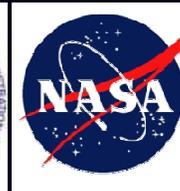


Important to view Cal/Val in the context of an end-to-end system and through the entire life cycle of the system



Calibration/Validation Activities

With a focus on L2 Product Validation...



Launch

Pre-Launch

Post-Launch

<i>Pre-launch Cal/Val</i>	<i>Early Orbit Check-out</i>	<i>Intensive Cal/Val</i>	<i>Long Term Monitoring & Operations</i>
Sensor characterization - Radiometric calibration - Geolocation/navigation	Post-Launch Tests (PLT) and engineering tests (compliance)	Established sensor stability	QC/QA processes in place
Proxy data generation	Calibration Processing; Analysis of L1b products	Sensor characterization - Radiometric calibration - Geolocation/navigation	Continuous assessment & monitoring, trend analysis of product quality
Algorithm assessment and verification	Quick look analysis of L2 products; comparisons to NWP model/analyses	Finalize L2 algorithm tuning and testing; Establish L2 product stability	Algorithm improvements
Determination of validation strategies, including identification and acquisition of "ground-truth"/reference datasets	Work to establish sensor stability; Work to establish L1b and L2 product stability; L1b and L2 algorithm testing and tuning	L1b/L2 product validation processes in place; L1b and L2 product validations	Full and continuous data release to the user community
Cal/Val tool development	Establish routine validation processes	Increasing data release to the user community	Cal/Val tool improvements
Development of L1b & L2 Cal/Val Plans	Data released to users, but data is understood to be non-operational	Cal/Val tool improvements	Data Archival
	Data Archival	Data Archival	

Today's Timeline (Current GOES):

~6 months

GOES-R Timeline: Not unrealistic to assume that more than 6 months will be needed



STAR/AWG Calibration/Validation Scope (Pre-Launch)



- STAR/AWG is participating on the GOES-R Cal/Val Team
 - Focus is on performance of GOES-R instruments
 - Ensure GOES-R L1b integrity
 - Provide technical support to the GOES-R Flight and Ground Projects
- Validation and Quantification of product performance
 - Specifically addressing the L2 product specifications (ie., *accuracy, precision*) since these have been allocated to the AWG
 - *Using proxy data* and comparing resultant products to other correlative data sources (in situ, NWP, satellite-based product, etc...)
- Development of product cal/val tools needed for
 - Routine product monitoring
 - “Deep-dive” assessments and analysis of products
- Continued Level-2 product demonstrations and validation studies
 - Establish routine generation of L2 products from ABI proxy data
 - Continue product validation
 - Outlier studies (identify stressing cases, algorithm improvements)



Routine Cal/Val Tools

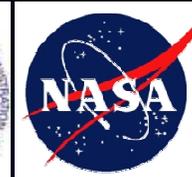


- Targeted for the routine and automated monitoring of operational Level-2 products
- Enable the visualization of products and/or reference (“truth”) data
- Perform the routine daily collocation of Level-2 products with their associated reference (“truth”) observations and the creation of comprehensive collocation databases
- Enable the generation and visualization of comparison statistics
- Rely on/built upon a variety of existing libraries that that enable data analysis and visualization capabilities
 - Man-computer Interactive Data Access System (McIDAS)
 - Interactive Data Language (IDL)
 - Java
 - Other

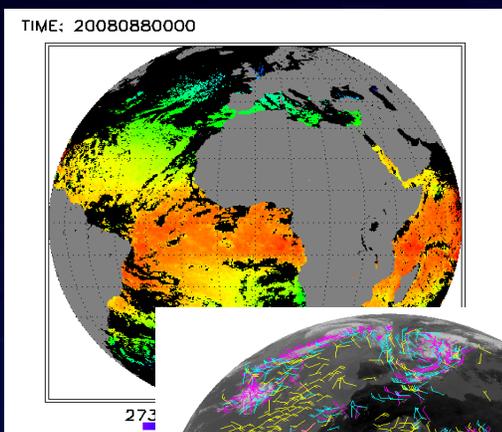


Routine Cal/Val Tools

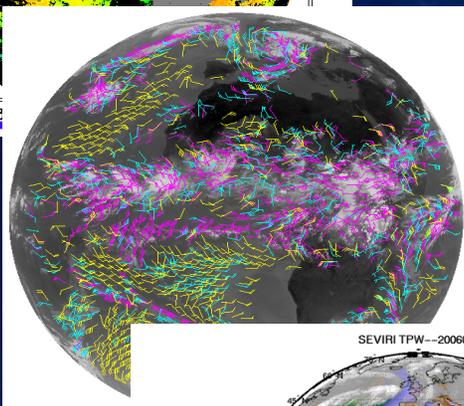
Some Example Output...



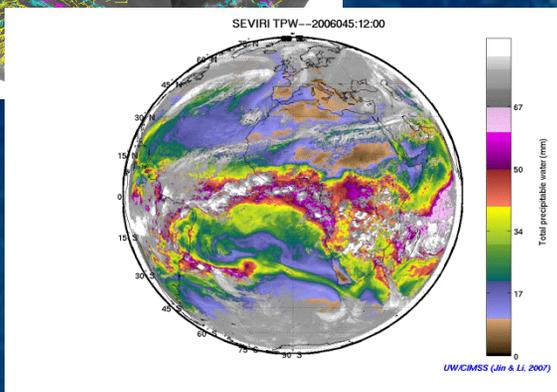
Product Displays



SST



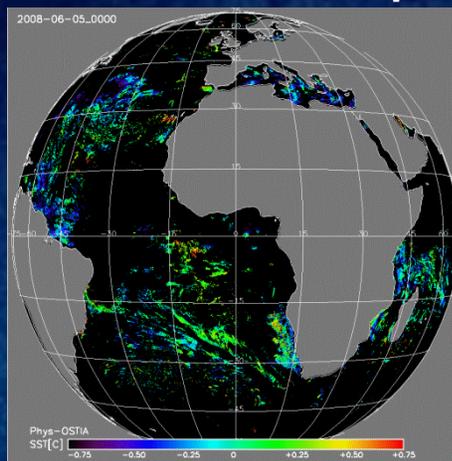
Winds



TPW

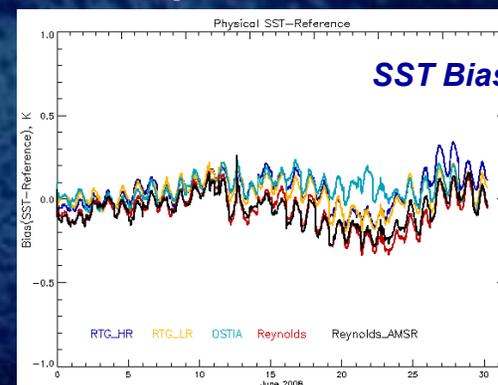
Retrieved Product – Reference/"Truth" Data

Horizontal Displays

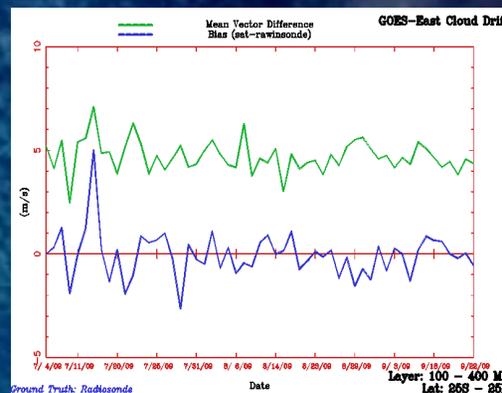


Retrieved SST – SST Analysis (UK Met Office)

Time Series of Comparison Statistics



Retrieved SST – 5 different reference SST datasets



Time series of mean vector difference and speed bias metrics between high level (100-400 hPa) GOES-12 infrared cloud-drift IR winds and radiosondes

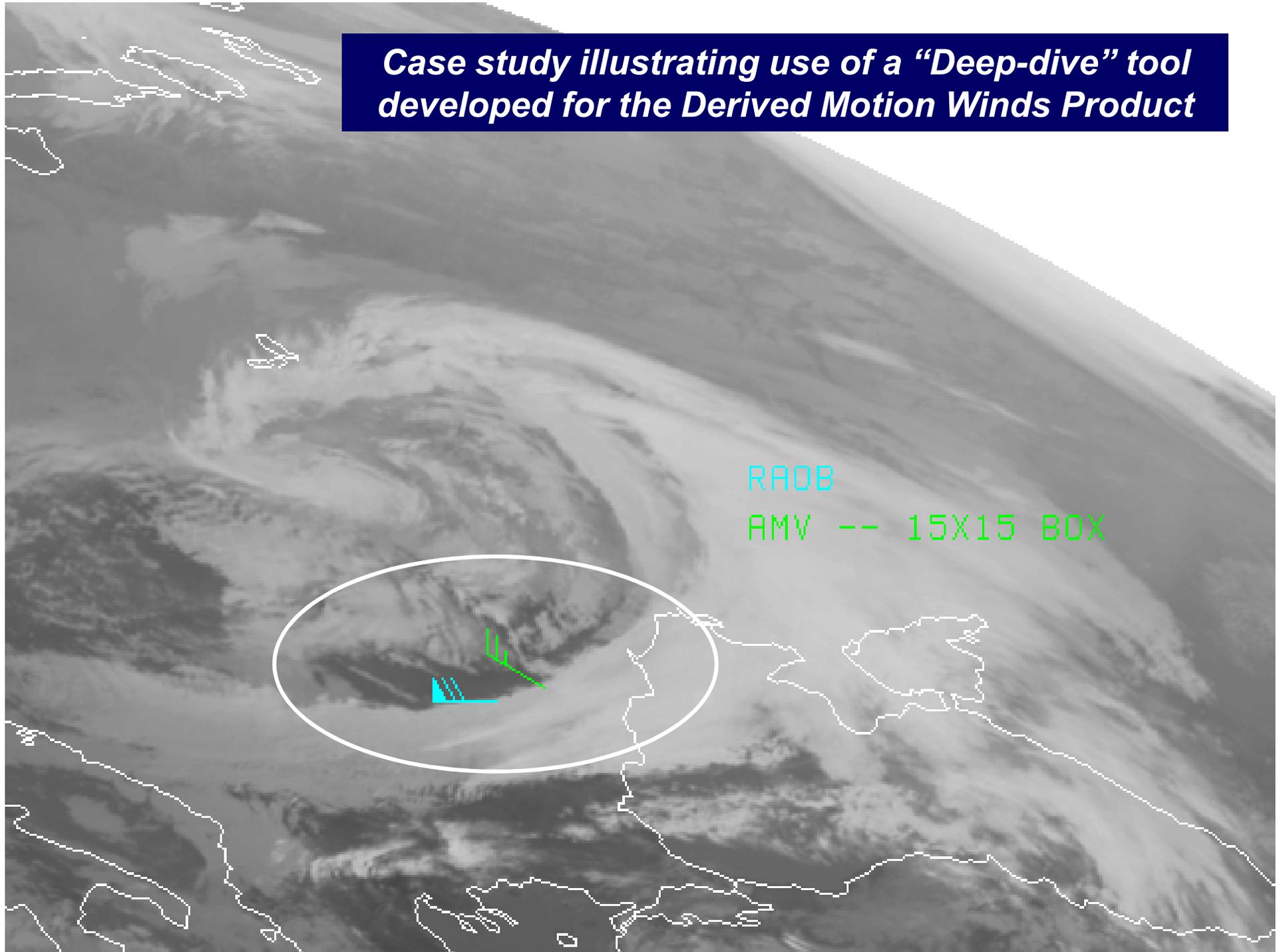


“Deep-Dive” Cal/Val Tools



- Set of customized tools targeted for “deep-dive” assessment of Level-2 products in the research and development environment
- Provide algorithm developers with the means to assess the performance of an algorithm, including any and all ancillary and intermediate data needed by the algorithm to generate the product
- Product reprocessing capability
 - In whole or individual retrievals
- Enhanced visualization capabilities that enable more detailed scientific analyses
- Rely on/built upon a variety of existing libraries that enable data analysis and visualization
 - Man-computer Interactive Data Access System (McIDAS)
 - Interactive Data Language (IDL)
 - MATLAB
 - Java
 - Other

Case study illustrating use of a “Deep-dive” tool developed for the Derived Motion Winds Product

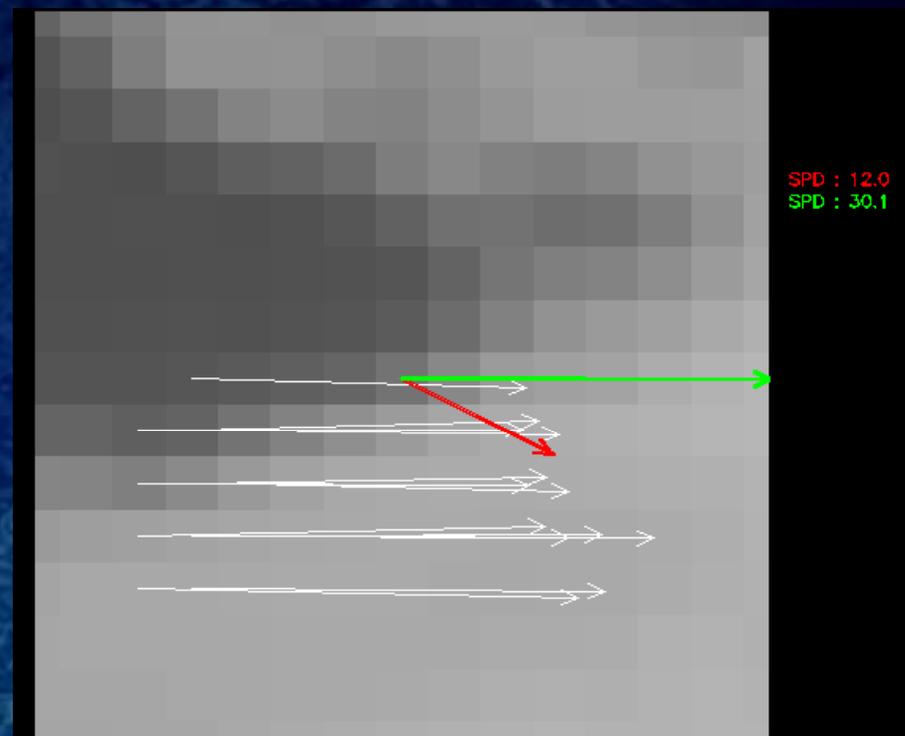




Example of a “Deep-Dive” Tool for the Derived Motion Winds Product



- Stand-alone tool that enables
 - The generation of a single derived motion wind vector for a single target scene
 - The display of the retrieved, guess, or ground truth wind vector over the target scene in question
- Here we were testing the nested tracking algorithm for case shown in previous slide and comparing the wind vector derived from it to the wind derived from the control algorithm



*Retrieved wind from control algorithm
(Speed: 12m/s)*

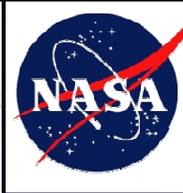


*Retrieved wind from the nested tracking algorithm where wind is derived from the sample of local wind vectors (in white)
(Speed: 30.1m/s)*

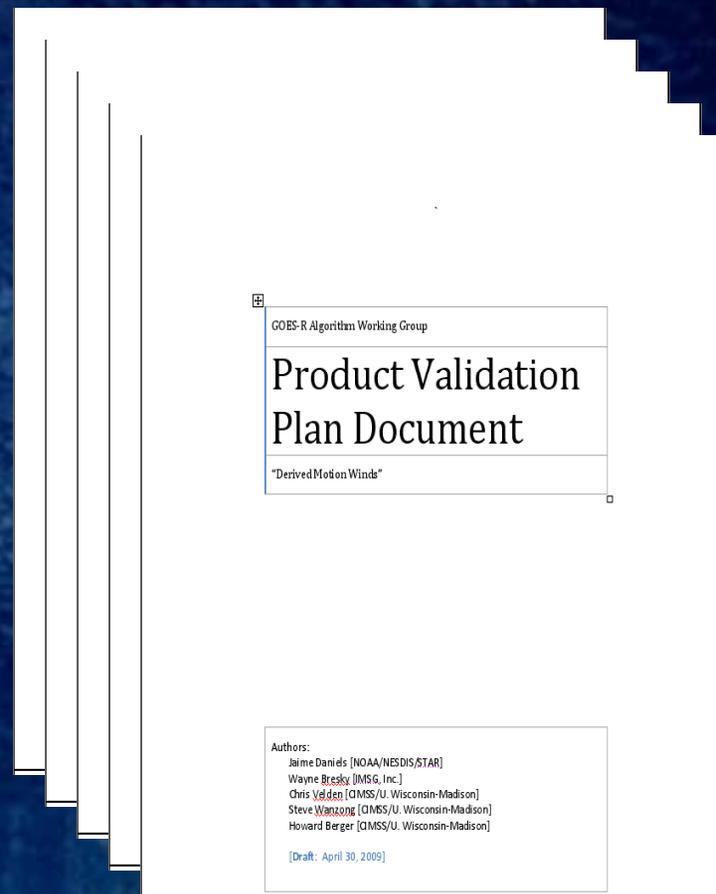


GOES-R L2 Product Cal/Val Plan

In Progress...



- AWG Product teams have prepared validation plans for *each* GOES-R Baseline Level-2 product they are responsible for
- Individual plans describe how each product will be validated during the pre-launch and post-launch phases of the GOES-R program
 - *Discuss validation strategies*
 - *Identify pre-launch and post-launch validation activities*
 - *Identify proxy data*
 - *Identify correlative data sources*
 - *Discuss validation tools to be developed*
- These individual Level-2 product validation plans are being folded into a Master GOES-R Product Cal/Val Plan
 - *Identify roles & responsibilities*
 - *Coordinated field campaigns*
 - *Schedule of activities*
 - *Community review and acceptance*





Summary and Planned Activities



- **AWG algorithm development activities are progressing well**
 - Baseline (100%) and Option-2 (80%) Level-2 product algorithm packages have been delivered to the GOES-R Program
 - Teams are working to refine the Option-2 Level-2 product algorithms and deliver 100% mature algorithms to the GOES-R Program (Sept 30, 2011)
 - Extensive collection of proxy and validation datasets established
 - Algorithm processing framework is in place
- **AWG is actively supporting the baseline Level-2 product algorithm implementation activity being done by the Harris Team**
- **AWG Next Steps**
 - Product application teams have identified and began development of Cal/Val tools (routine & deep-dive)
 - Increased validation efforts
 - Outlier studies and analysis
 - Support GOES-R Proving Ground Demonstrations (User Readiness and Training)